

# OCTOPUS

| MAIN FUNCTIONS                                     |  |
|--|--|
| <b>System</b>                                      | Multi-monitor software   |
|  | Touch screen mode  |
|  | Backup/recovery of settings, files and cartography   |
|  | Automatic reload of the last environment on startup  |
|  | Automatic detection of cable instruments   |
|  | Automatic sending of waypoint data to the instruments displays                                 |
| <b>Navigation</b>                                  | In/out communication with WIFI device  |
|  | Calibration of instruments (log, compass and windvane)   |
|  | Waypoints & routes management  |
|  | Charts compatibility: electronic vector charts (C-Map MAX) and raster charts (SnMap, BSB)      |
|  | Automatic creation of waypoint on C-Map buoy   |
|  | Search tool on the chart for ports, waypoints or roadbooks                                     |
|  | GRIB files download online and by email up to 16 days  |
|  | NOAA, Predictwind, Tidetech and Great Circle direct interface                                  |
|  | Global tide module   |
|  | Tide charts compatibility: SHOM, Proudman (+ high resolution), Winning Tides                   |
|  | Display of weather and tide conditions on mooring  |
|  | Display of the route on the opposite tack  |
|  | Logbook (position, wind, speed and observations)   |
|  | Roadbook with possibility to add visual annotations on the chart                               |
|  | Data export to Google Earth  |
|  | Superimposition of georeferenced images  |
| Meteogram  |  |
| Import/export of GPX files                         |  |
| Sending calculated data to iPhone or iPad          |  |
| <b>Security</b>                                    | Man over board tracking with drift calculation   |
|  | Sart AIS MOB detection   |
|  | Safety alarms: MOB, AIS, coast detection, anchor drag alarm                                    |
|  | Custom alarms: depth, wind force and direction, wp, etc.                                       |
|  | AIS Anti-collision system  |
| <b>Routing</b>                                     | Best route calculation while automatically avoiding coastlines                                 |
|  | Routing in 2 clicks  |
|  | Dual Routing: sailing and motoring   |
|  | Integration of tide/current data in routing calculations                                       |
|  | Possibility to set up min/max values in routing calculation: wind speed/angle and waves height |
|  | Table of legs: routing(s) summary  |
|  | Display of encountered conditions: wind, current, tide and waves                               |
|  | Best route calculation according to a given time of arrival                                    |
|  | Display of day/night periods   |
|  | Routing calculation of a route with several waypoints  |
|  | Simulation of several simultaneous routings  |
|  | Use of several GRIB files in routing calculation   |
|  | Routing hypothesis on time of departure/arrival, max wind/waves                                |
|  | Statistics on routing: wind, points of sailing, comfort  |
| Use of a different polar for day and night periods |  |
| Possibility to draw exclusion areas (Roadbook)     |  |
| <b>Polar</b>                                       | Real polars calculation from navigation data   |
|  | VPP polar diagrams creation  |
|  | Sails use charts management (Sailect)  |
|  | Possibility to correct recorded tracks   |